

Pinturas piezoeléctricas.

Nuevas perspectivas y aplicaciones

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III Semana de Iniciación a la Investigación Nebrija (del
7 al 11 de junio de 2021)

The background of the slide is a close-up photograph of a prehistoric cave wall covered in paintings. The most prominent feature is a large red bull, painted in a reddish-brown hue. The surface of the rock is cracked and textured, with various other smaller paintings and natural rock formations visible in shades of yellow, orange, and brown. In the top-left corner, there are four white decorative symbols: a solid circle, a large 'X' shape, a solid circle, and another solid circle.

¿Para qué sirve una pintura?



¿Para qué sirve una pintura?



¿Para qué sirve una pintura?

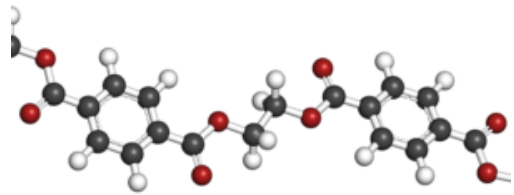


¿Y si ...?

Hagamos magia...



Aditivos



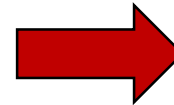
Polímero
(resina)



+

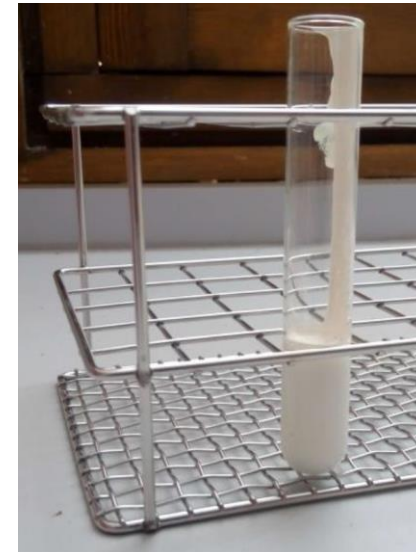


solvente



Material activo
(polvo piezoeléctrico)

Pintura
piezoeléctrica





Piezoelectricidad

David Brewster (1824)



Sal de Seignette

Piezoelectricidad

Familia Curie, Pierre, Jacques, Marie. (1881)



Turmalina



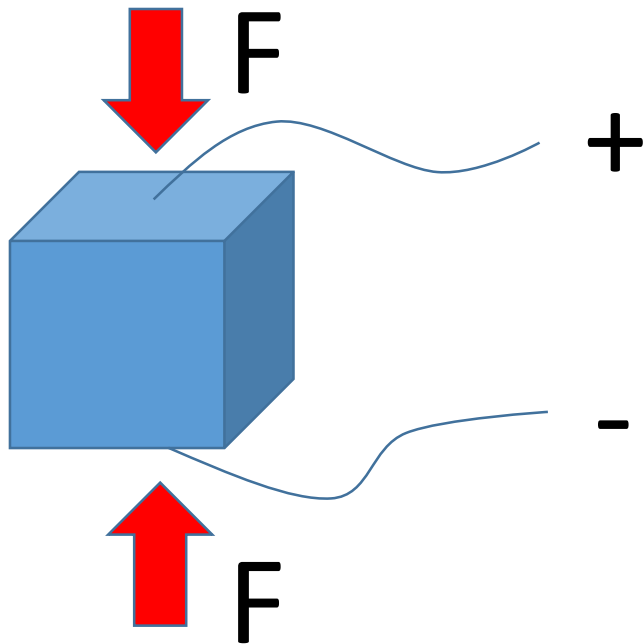
Cuarzo



Piezoelectricidad

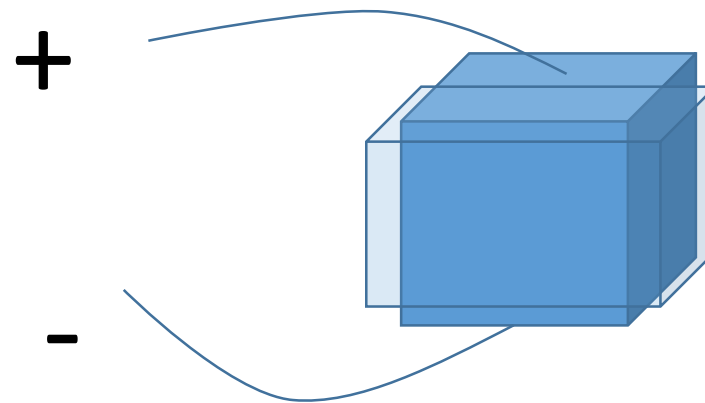
Efecto directo

$$D = K \cdot \sigma$$



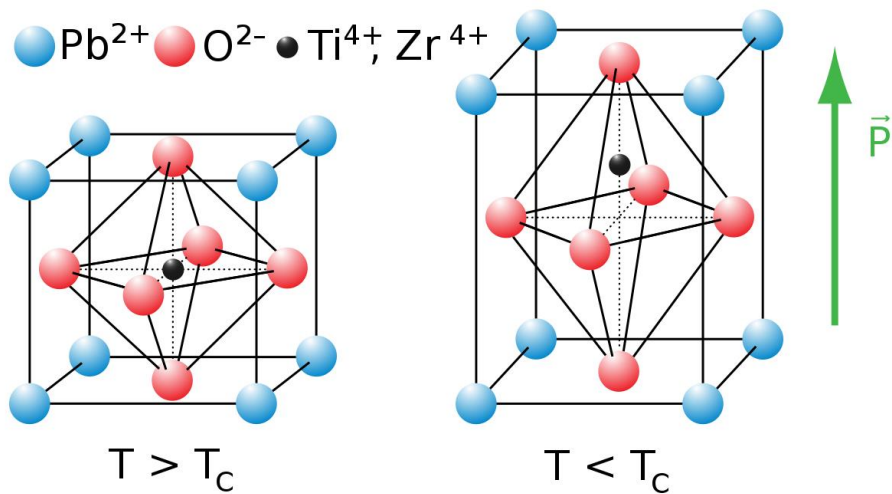
Efecto inverso

$$S = G \cdot V$$



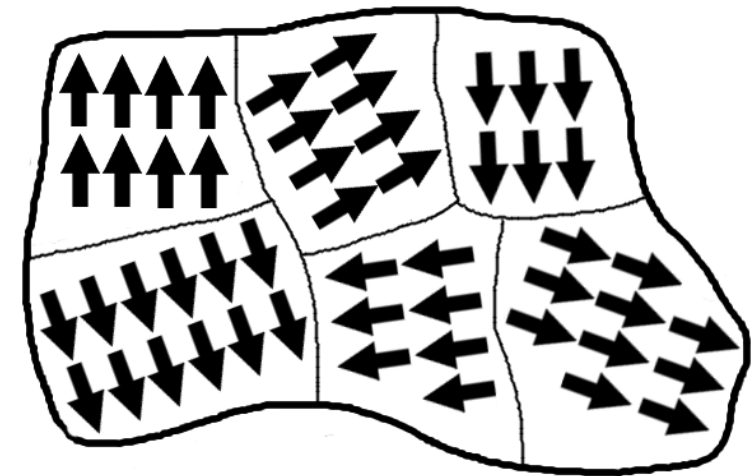
¿Cómo funciona la pintura?

Estructura cristalina asimétrica

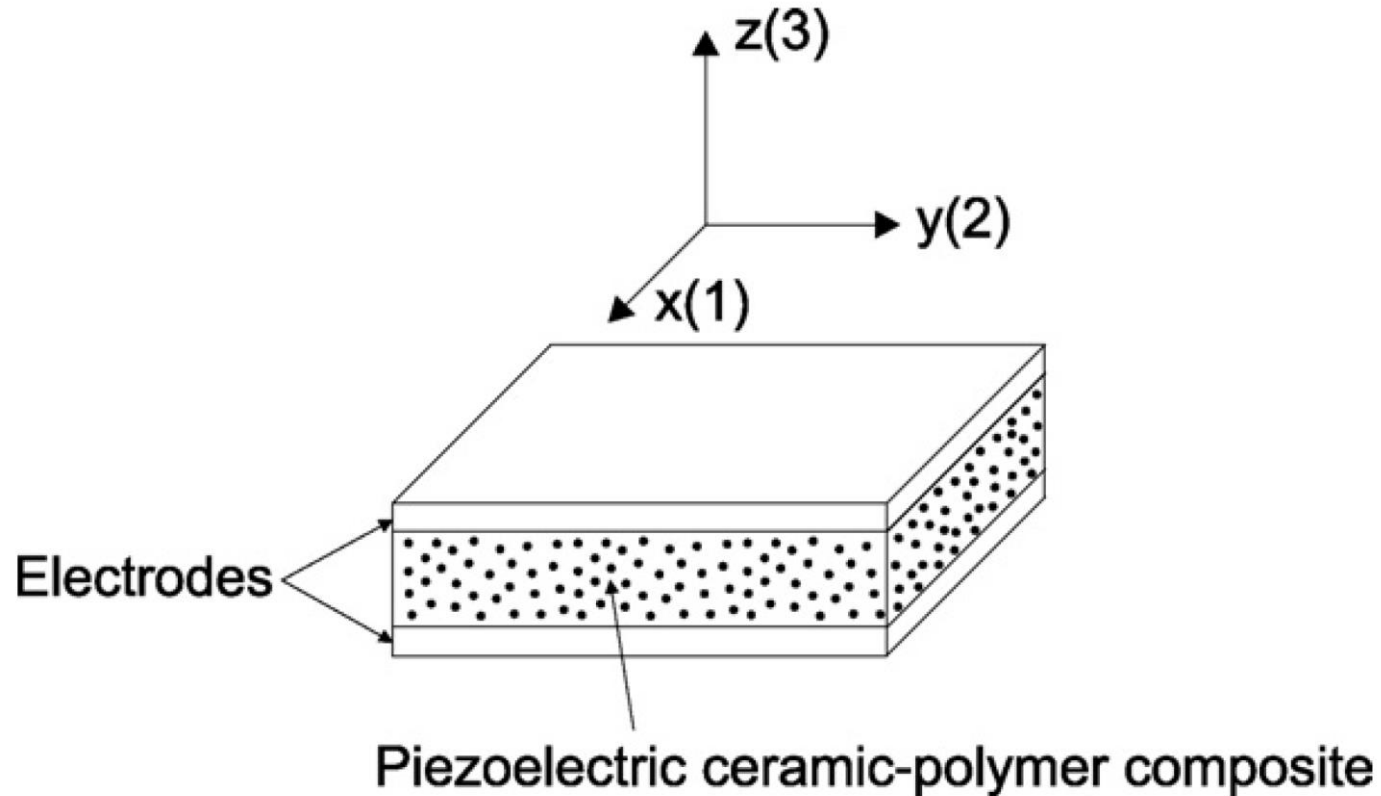


PZT (Zirconato titanato de plomo)

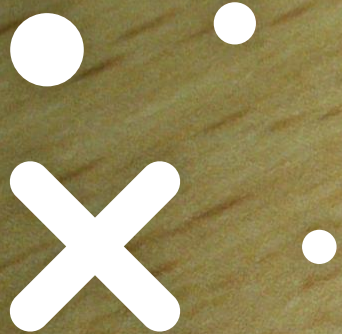
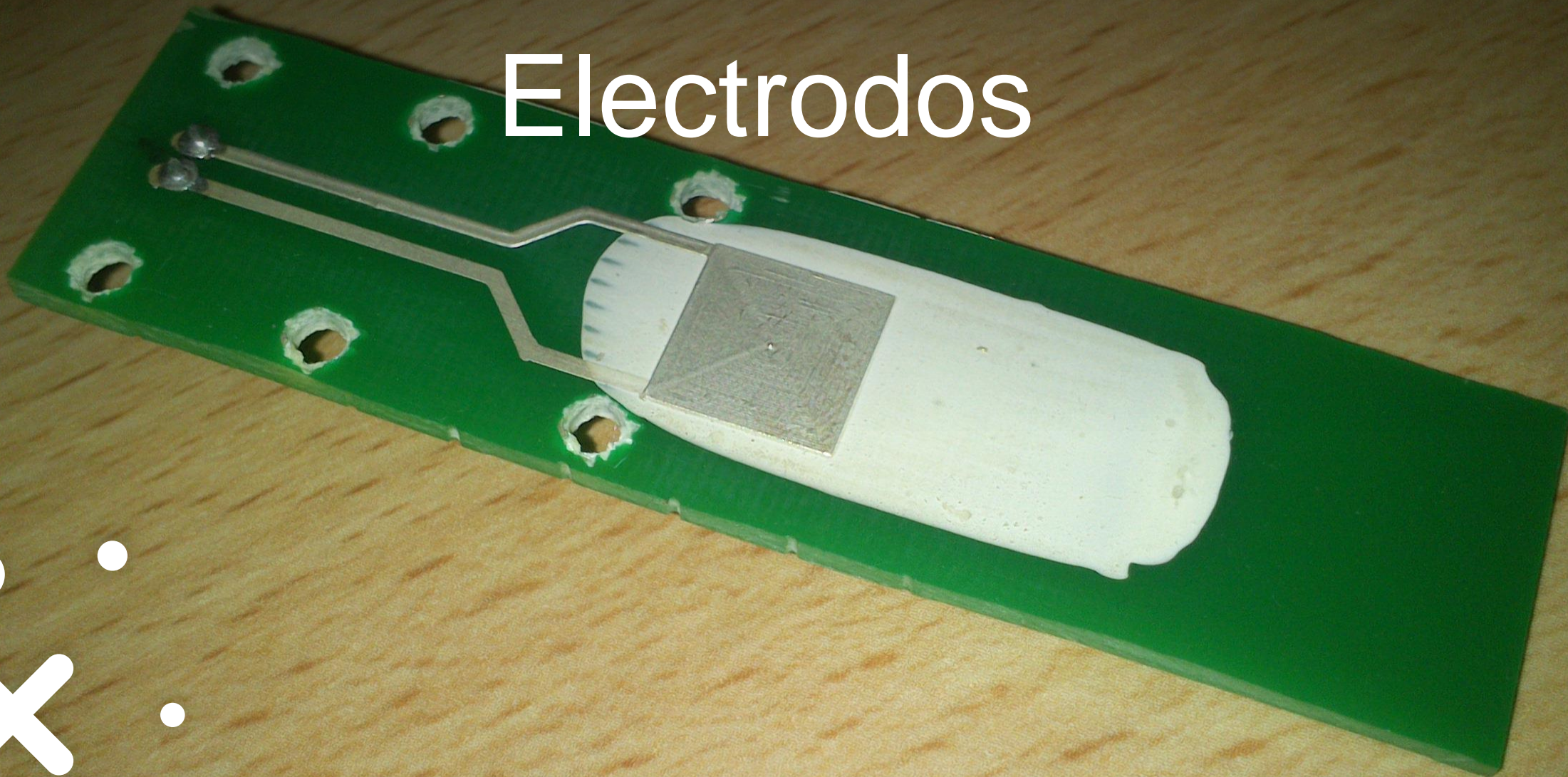
Dominios de Weiss



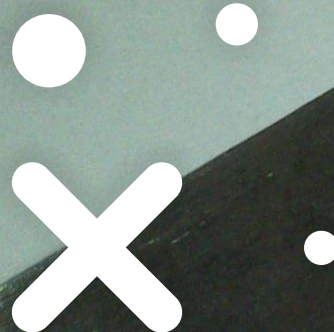
¿Cómo funciona la pintura?



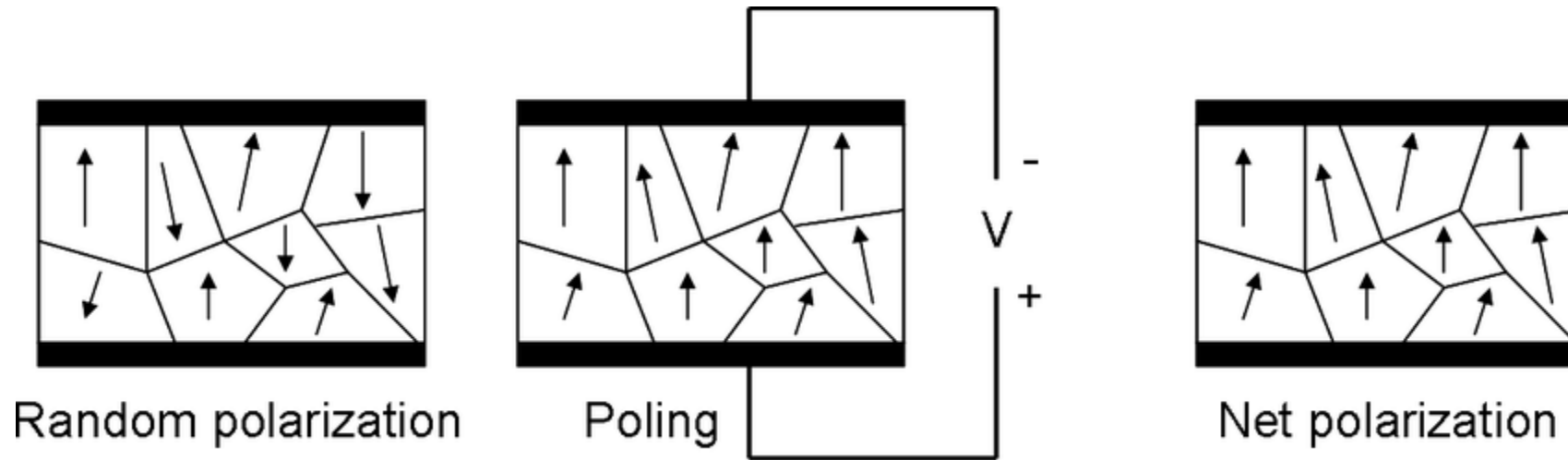
Electrodos



Electrodos



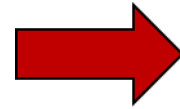
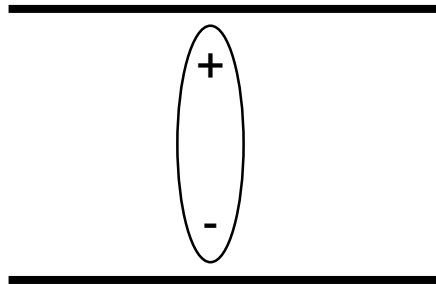
¿Cómo funciona la pintura?



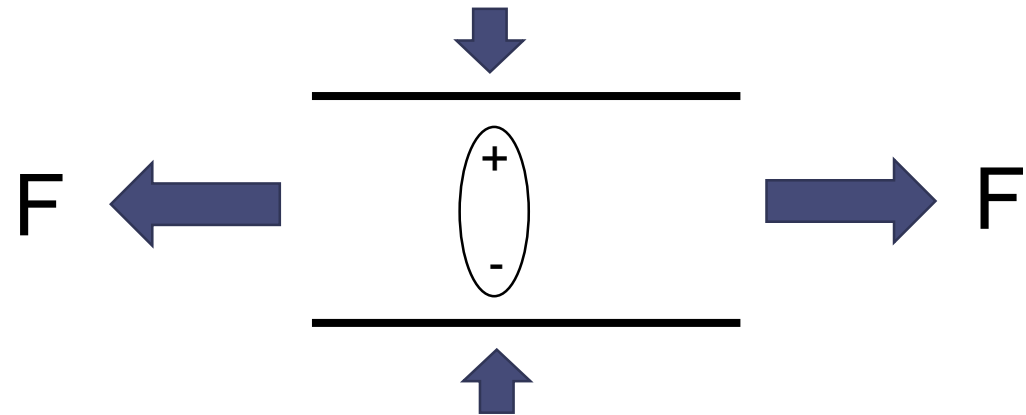
PZT material ferroeléctrico

¿Cómo funciona la pintura?

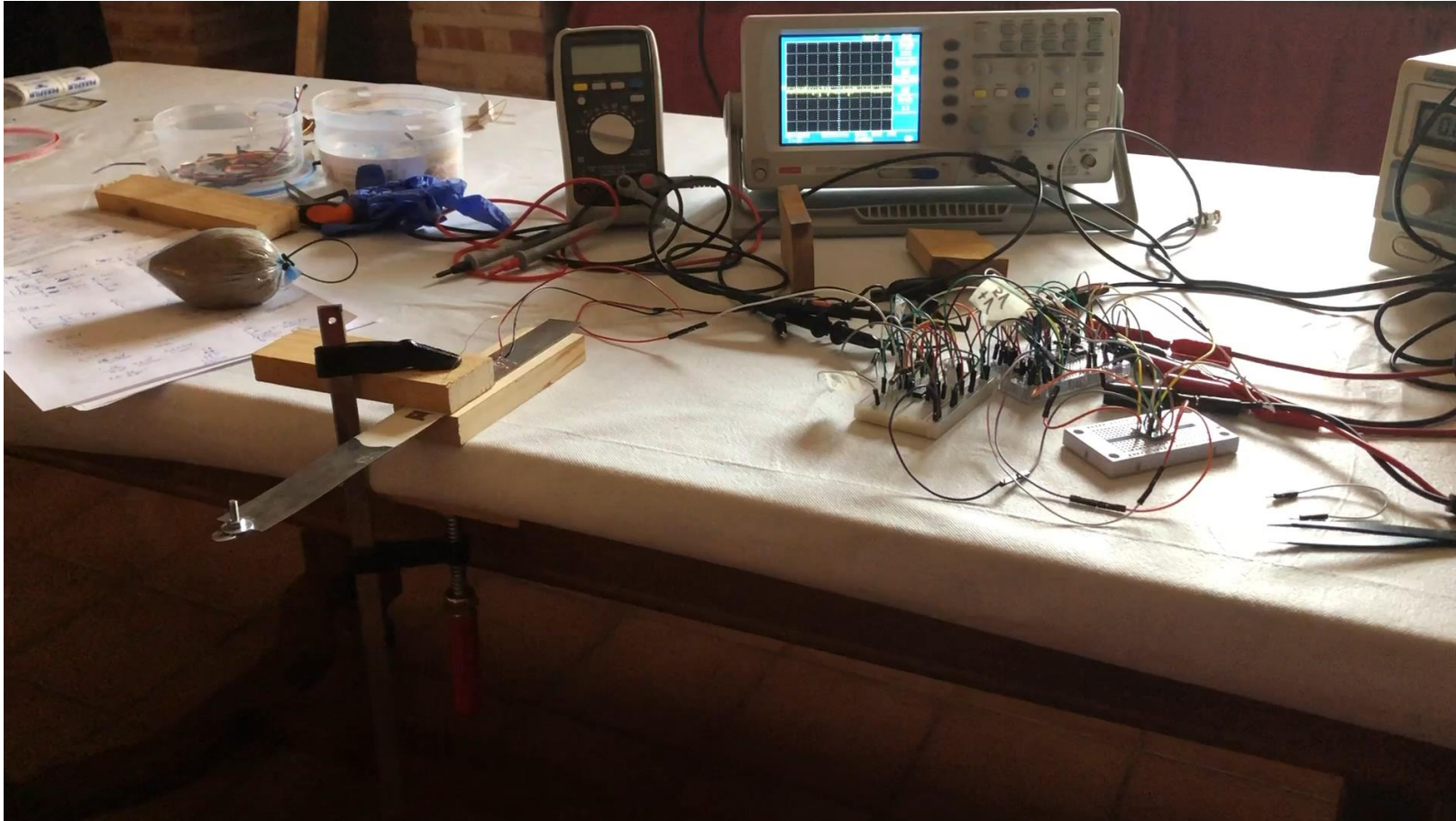
Cambio en el momento dipolar



Generación campo eléctrico



¿Cómo funciona la pintura?





Aplicaciones

Vibraciones estructurales

Y

Salud estructural



Aplicaciones

Recuperación de energía

Aplicaciones

Recuperación de energía



Mutsuda et al. 2017

X Pintura piezoeléctrica

Ventajas

Posibilidad de cubrir grandes superficies

Se puede aplicar a cualquier superficie

No hace falta adhesivo

Es flexible

No necesita fuente de energía externa

Diferentes propiedades

Desventajas

Baja sensibilidad

Sensibilidad depende de muchos parámetros

No distingue direcciones de deformación

No vale para medidas estáticas

Modelo electromecánico

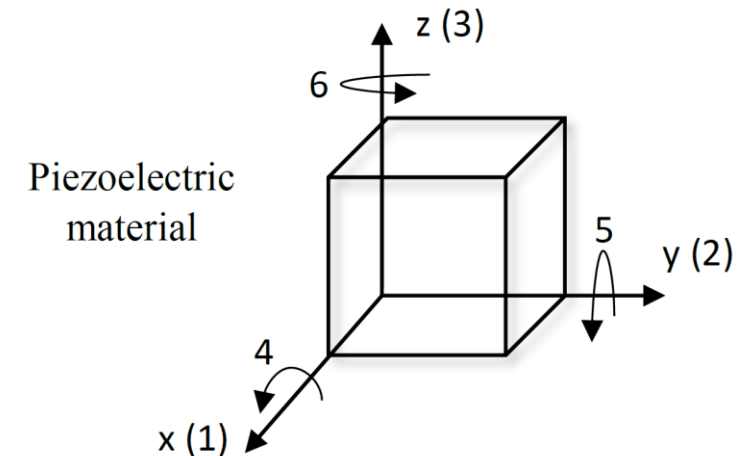
$$D_i = d_{ik}\sigma_k + \varepsilon_{ij}^\sigma F_j$$

Asumiendo:

$$F = 0$$

$$\sigma_3 = 0$$

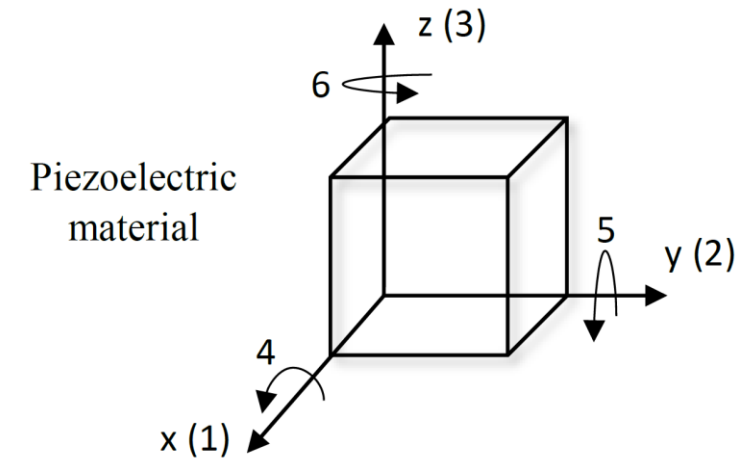
Dirección de polarización (eje z)



Modelo electromecánico

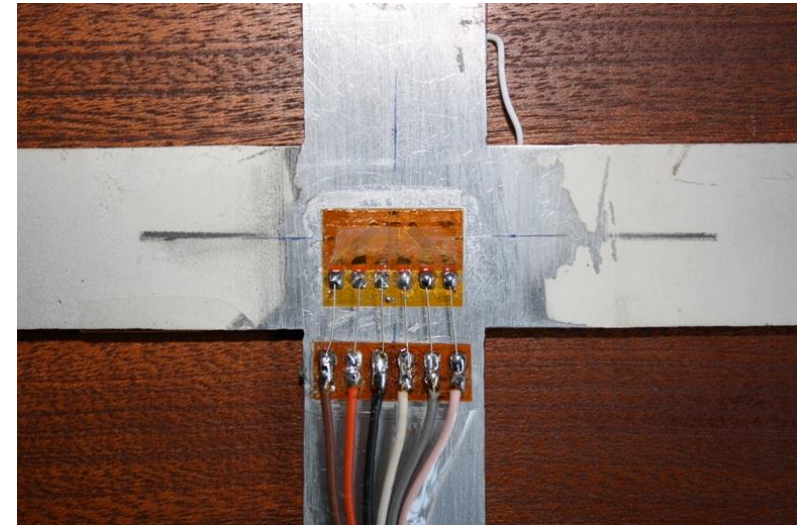
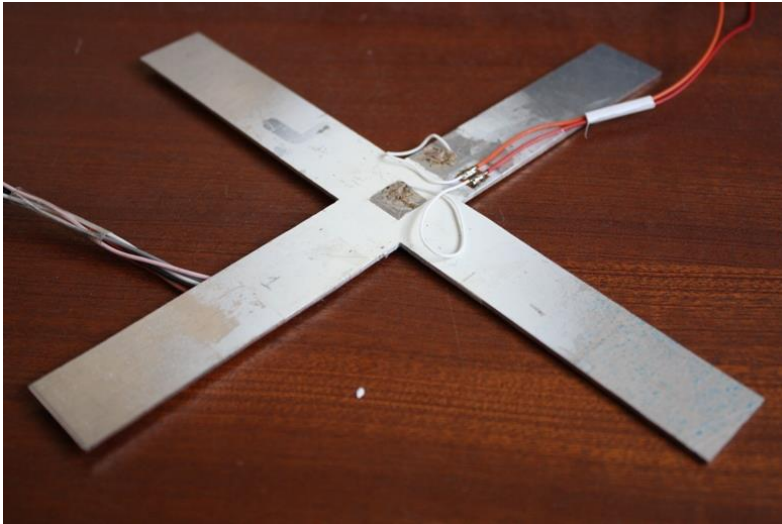
$$D_3 = d_{31} \frac{E}{1 - \nu} (\varepsilon_1 + \varepsilon_2)$$

$$S = \frac{D_3}{(\varepsilon_1 + \varepsilon_2)}$$



Validación experimental

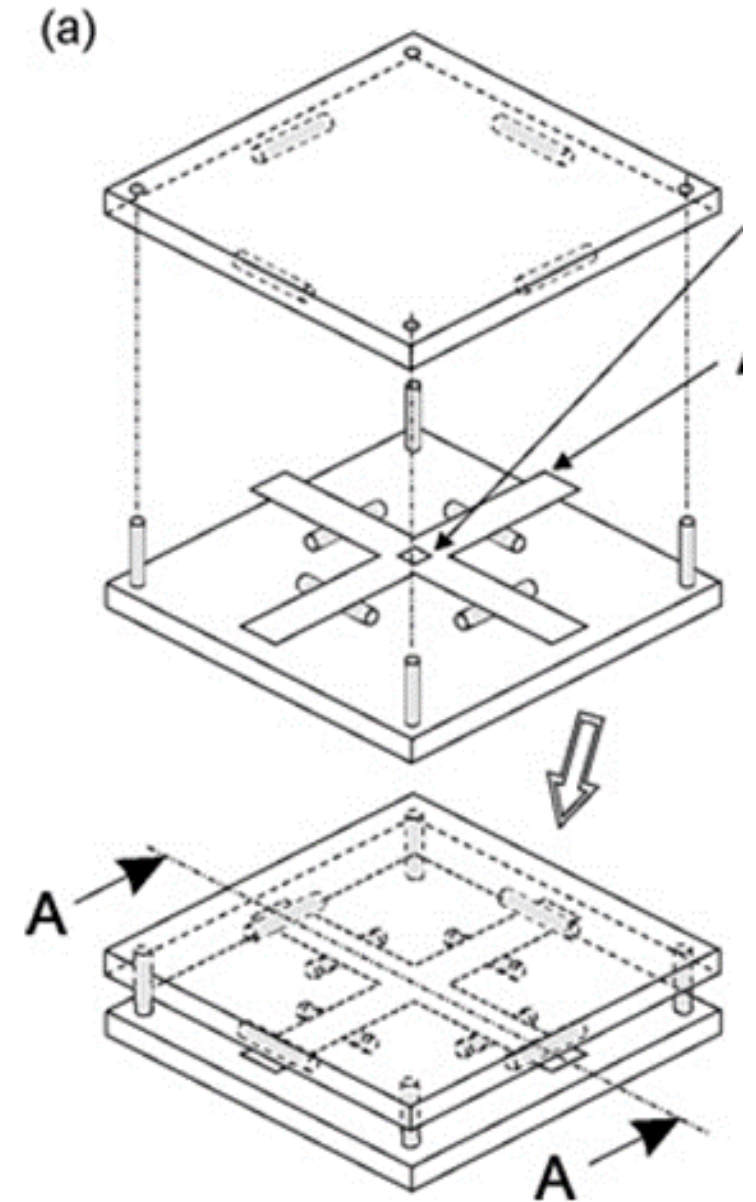
Prototipo experimental





Validación experimental

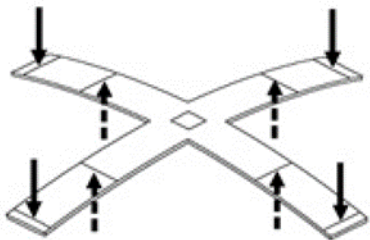
Prototipo experimental



Validación experimental

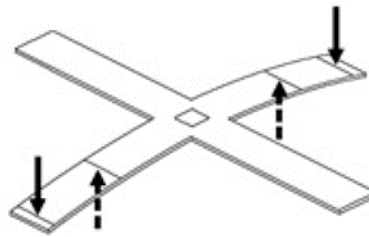
Experimentos

Experiment 1



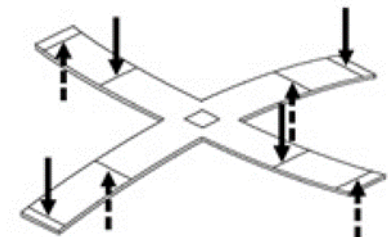
Biaxial positive bending moment

Experiment 2



Uniaxial positive bending moment

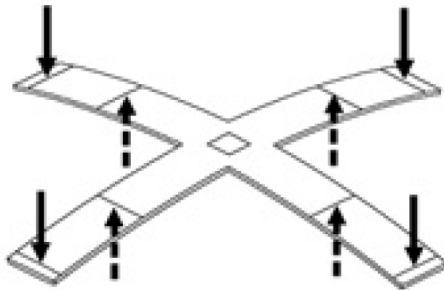
Experiment 3



Biaxial opposite bending moment

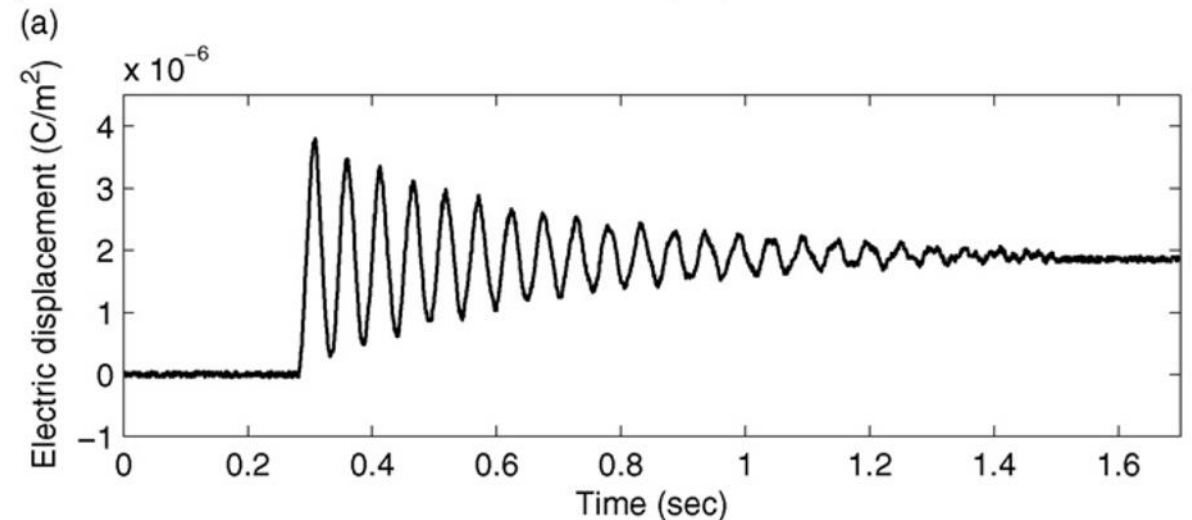
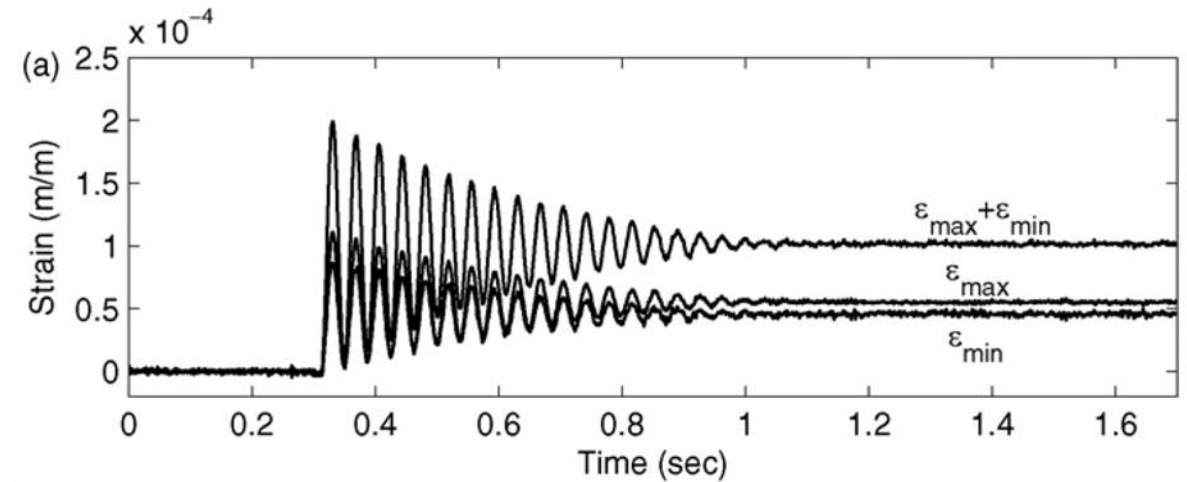
Validación experimental

Experiment 1



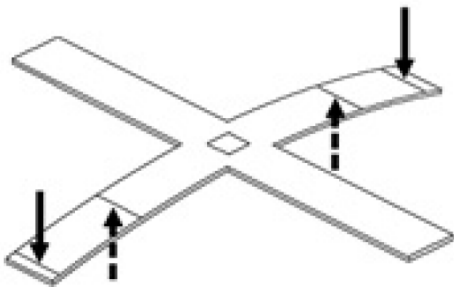
Biaxial positive
bending moment

$$D_3 = d_{31} \frac{E}{1 - \nu} (\varepsilon_1 + \varepsilon_2)$$



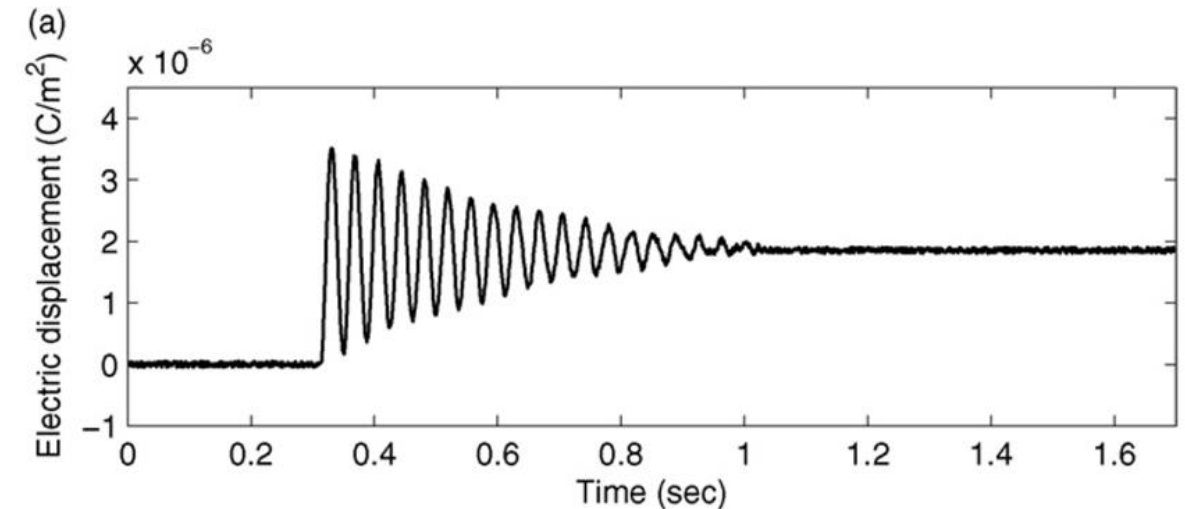
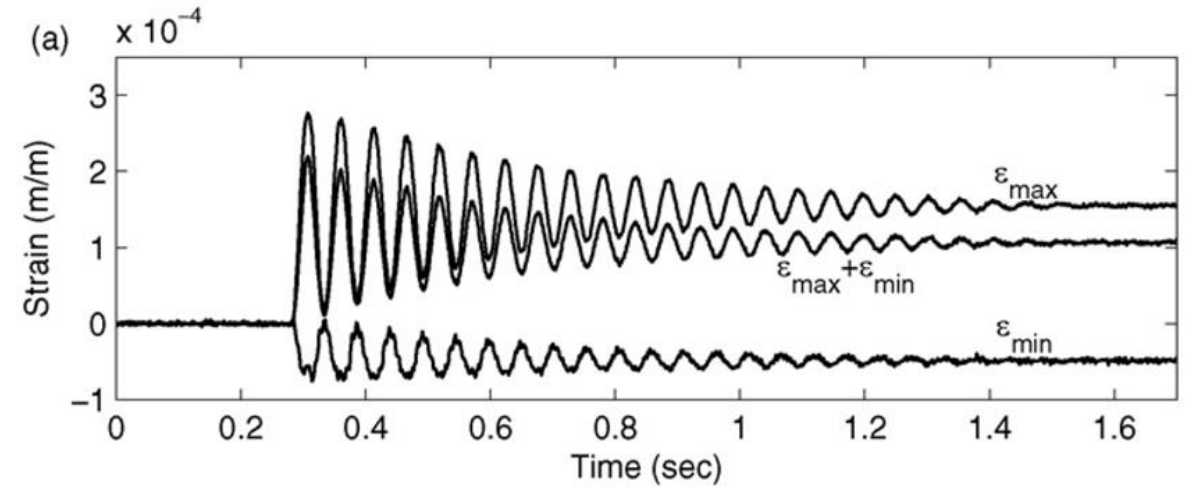
Validación experimental

Experiment 2



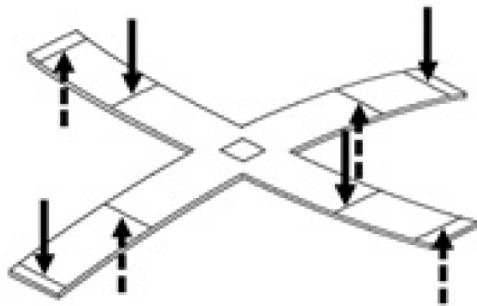
Uniaxial positive
bending moment

$$D_3 = d_{31} \frac{E}{1 - \nu} (\varepsilon_1 + \varepsilon_2)$$



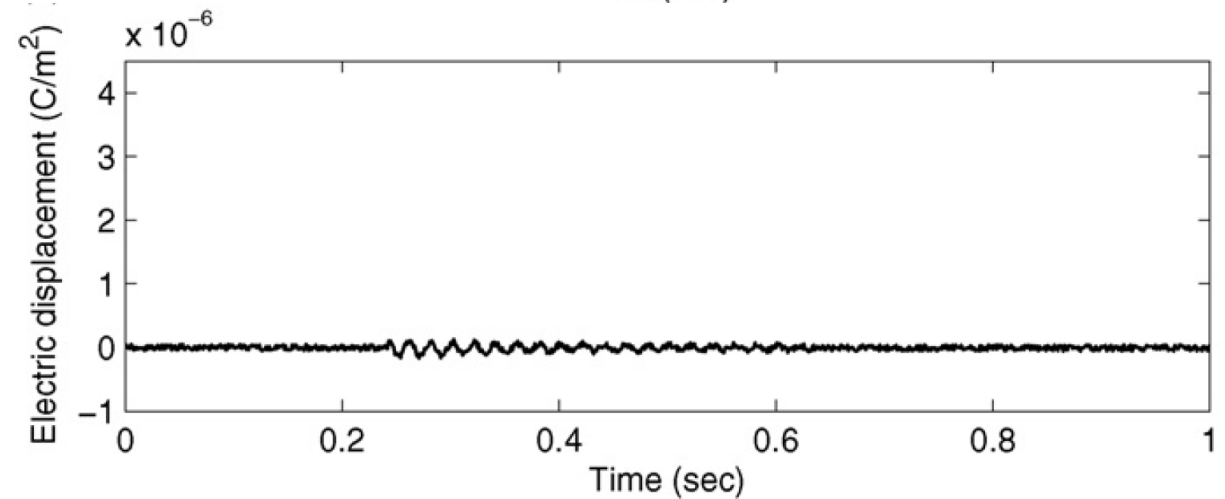
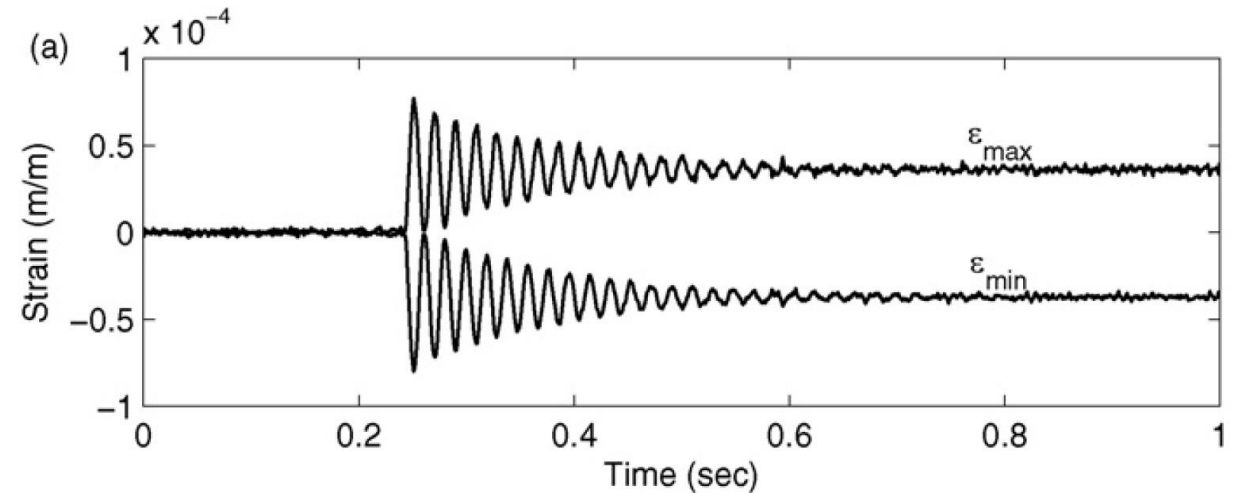
Validación experimental

Experiment 3



Biaxial opposite
bending moment

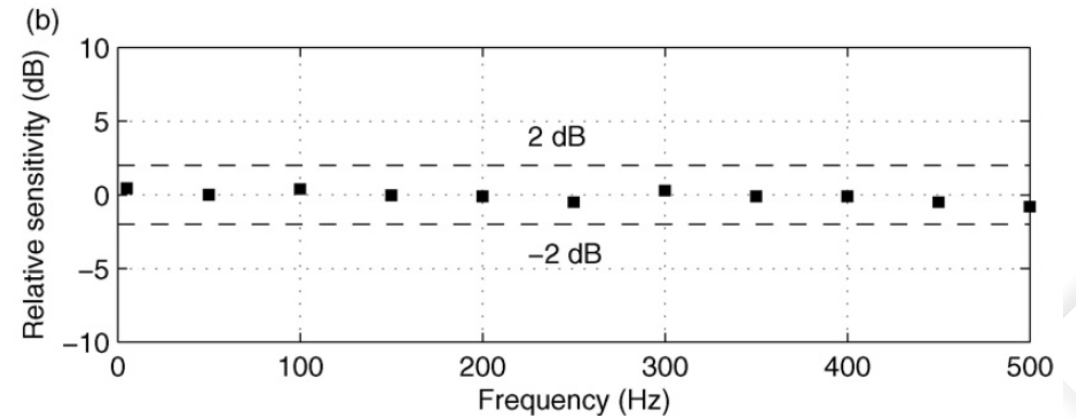
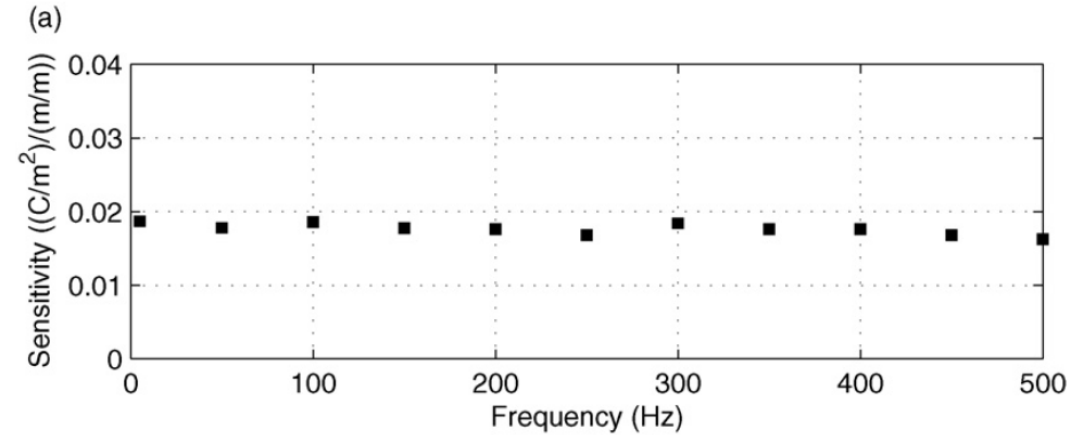
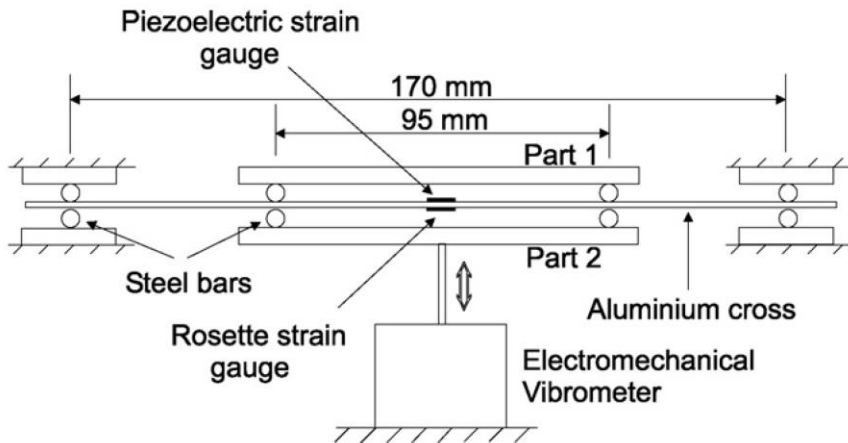
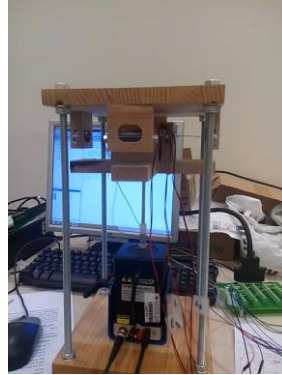
$$D_3 = d_{31} \frac{E}{1 - \nu} (\varepsilon_1 + \varepsilon_2)$$



Validación experimental

Sensibilidad vs. frecuencia

$$S = \frac{D_3}{(\epsilon_1 + \epsilon_2)}$$

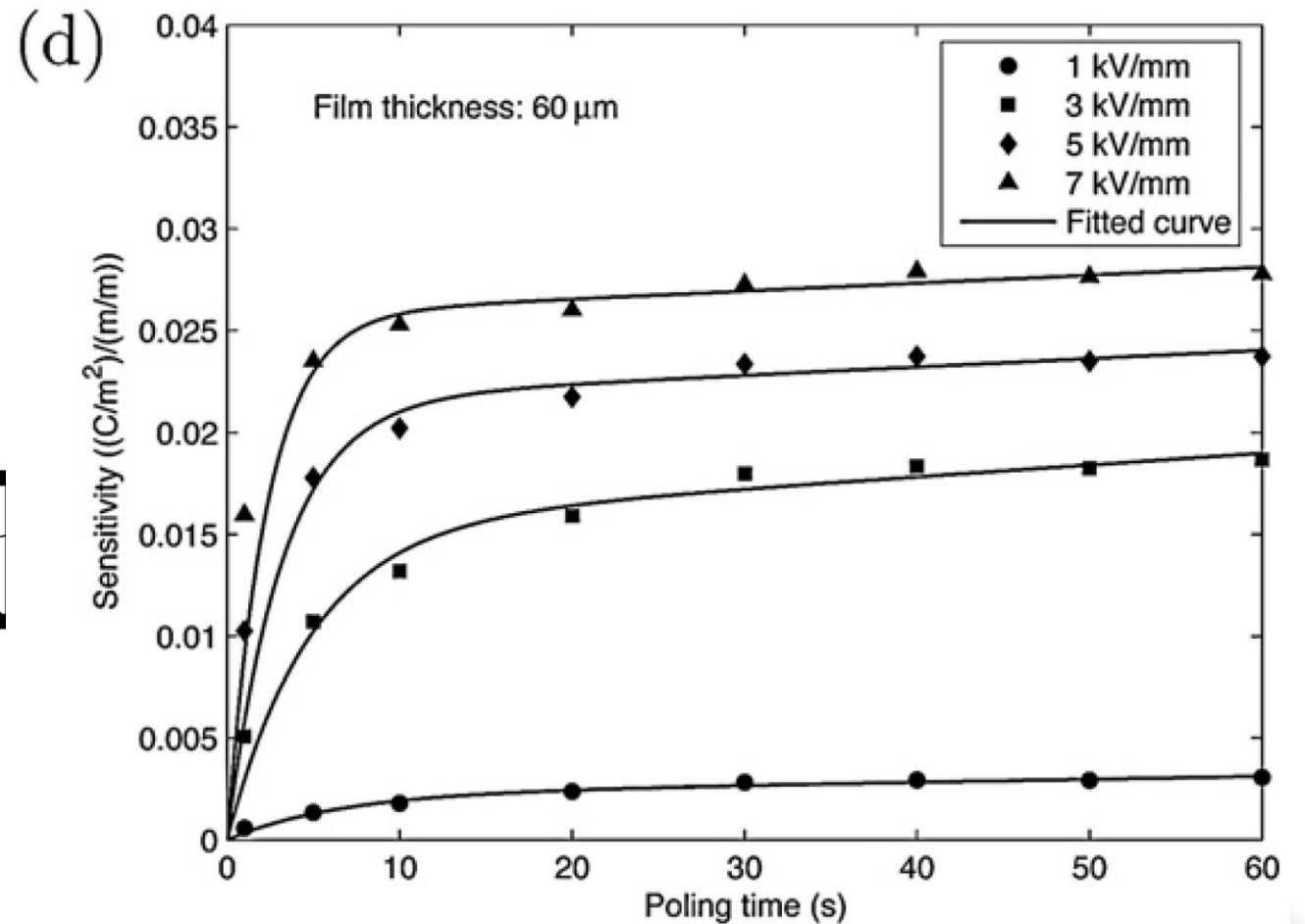
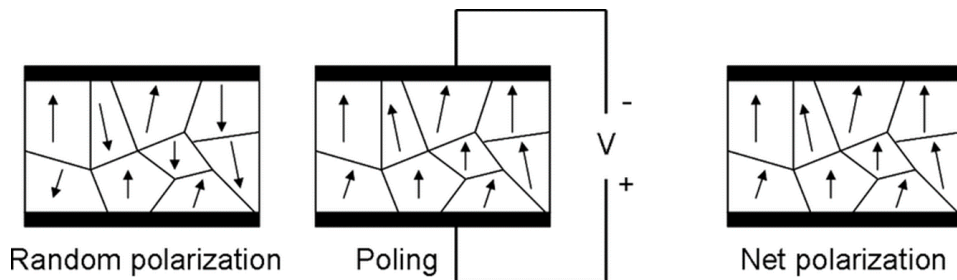


Análisis de la sensibilidad

$$S = \frac{D_3}{(\varepsilon_1 + \varepsilon_2)}$$

Parámetros que influyen:

- Polarización (campo eléctrico y tiempo aplicado)



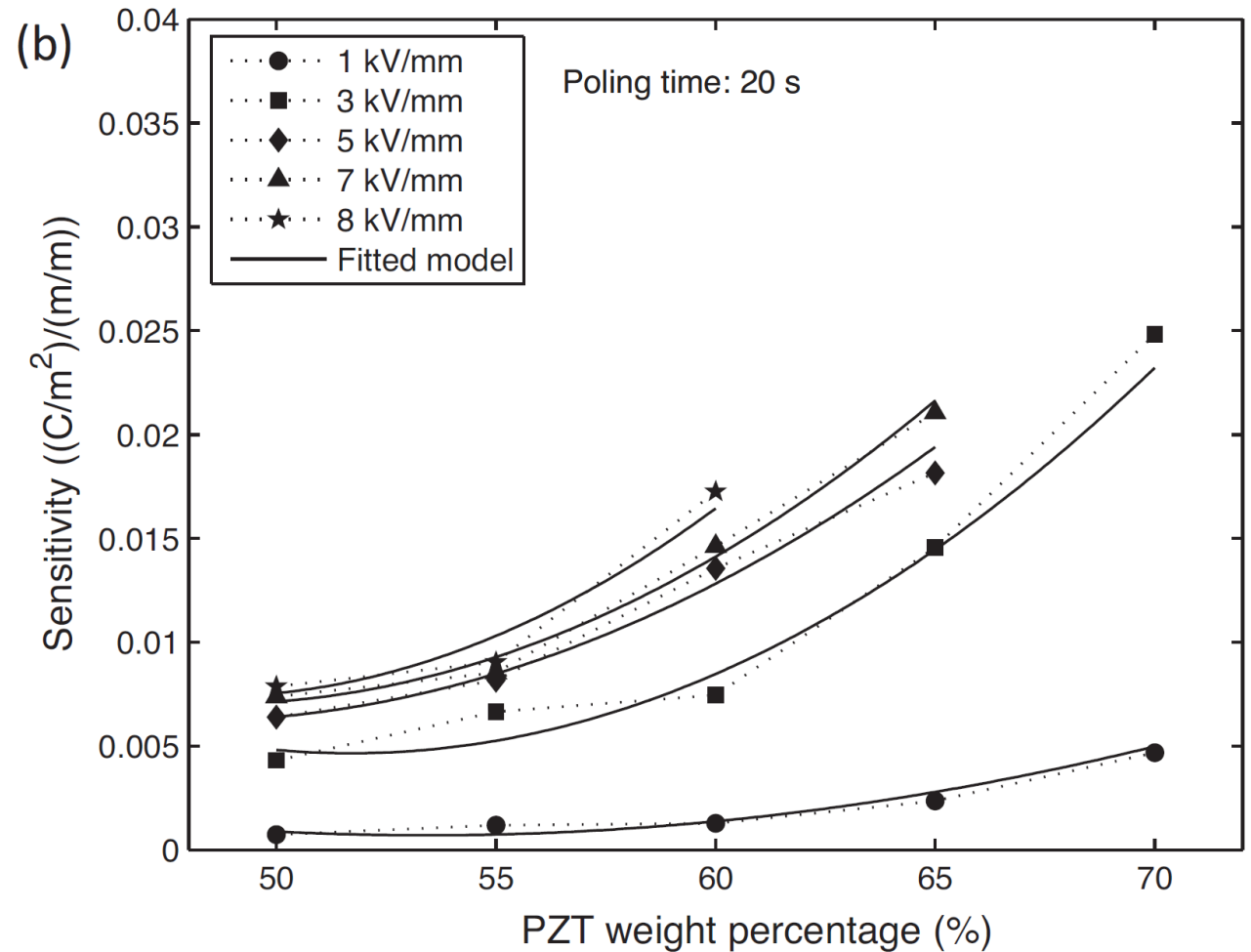
Análisis de la sensibilidad

Parámetros que influyen:

- % polvo piezoeléctrico



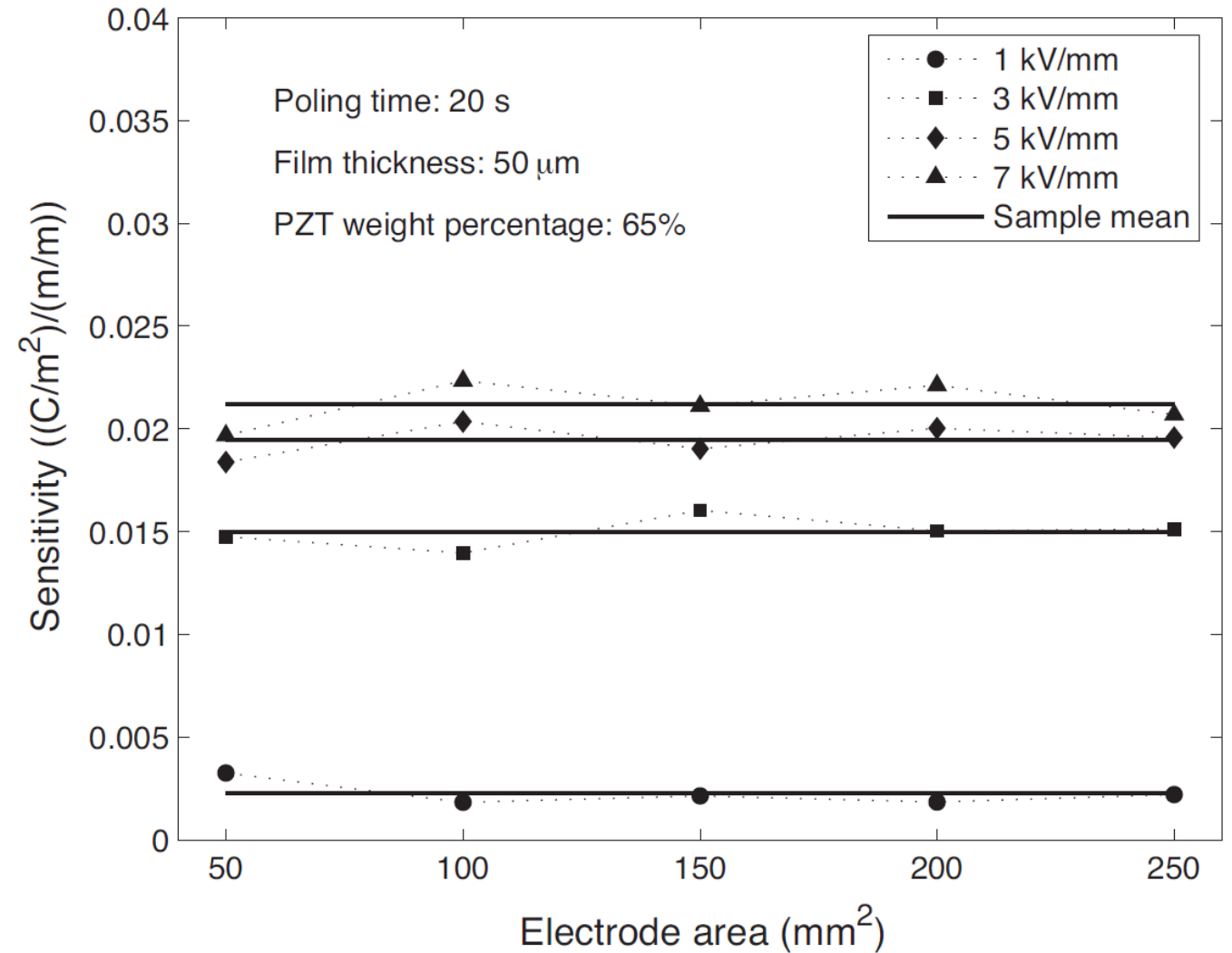
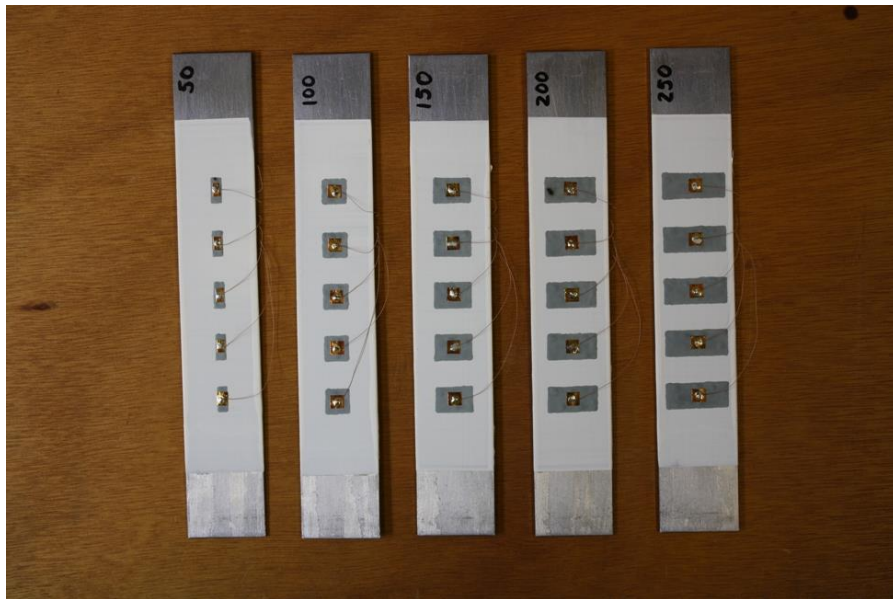
Material activo
(polvo piezoeléctrico)



Análisis de la sensibilidad

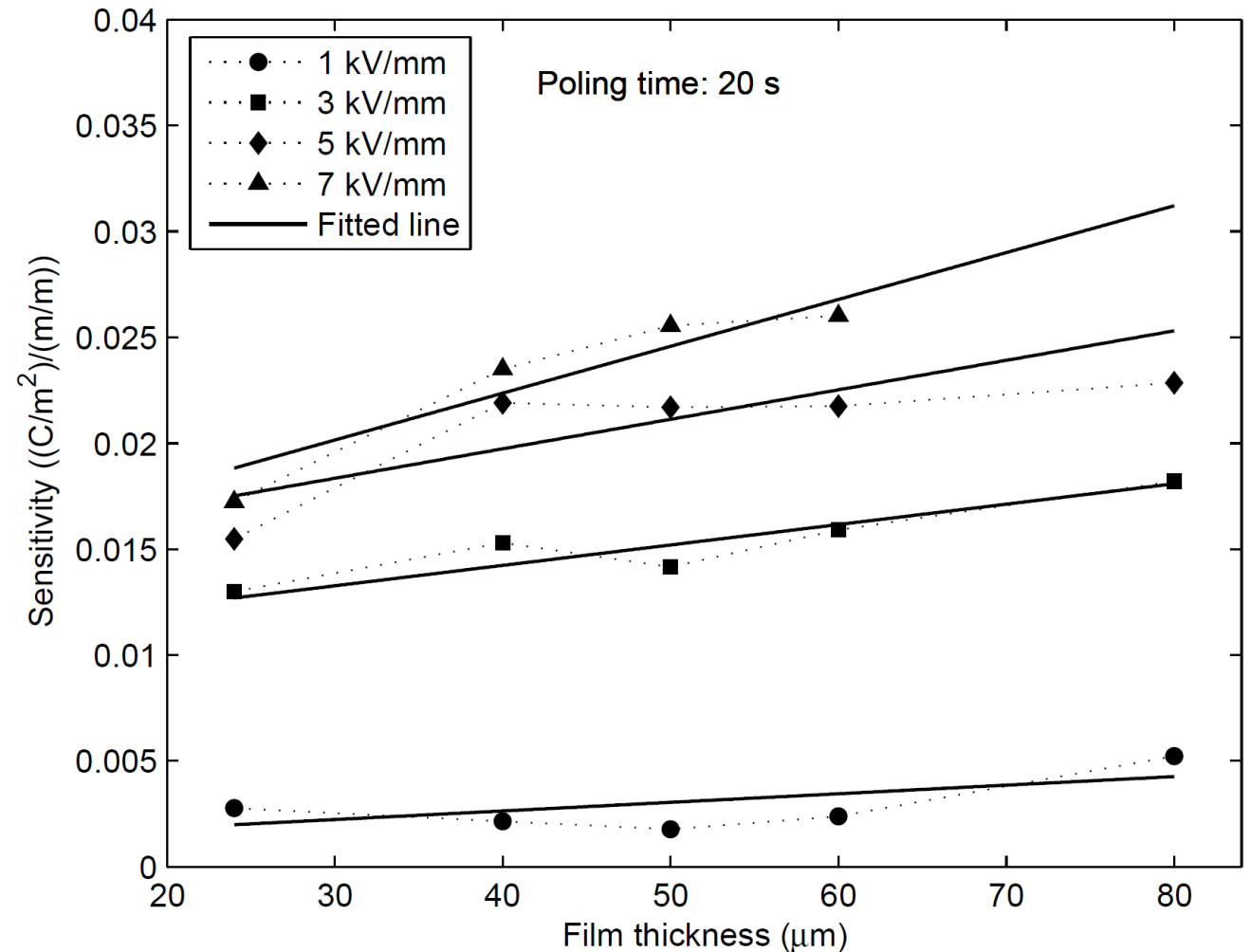
Parámetros que influyen:

- Área del electrodo



Análisis de la sensibilidad

Parámetros que influyen:
- Espesor de la pintura

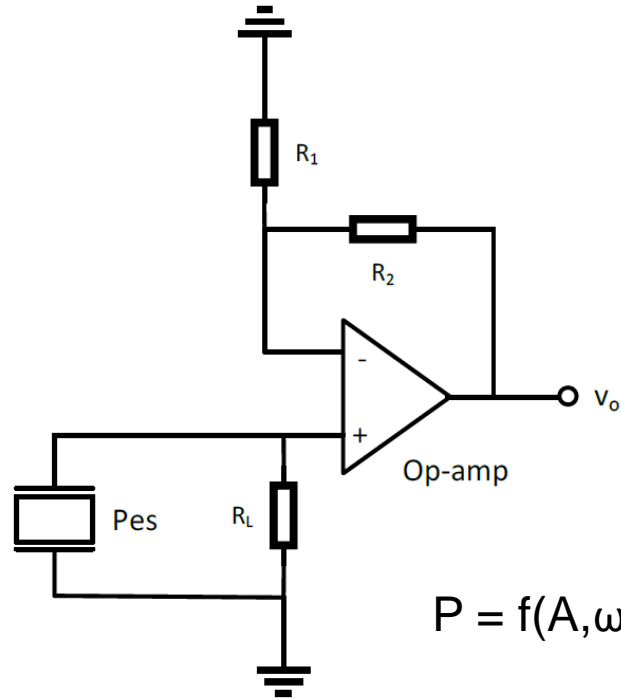


Análisis de la sensibilidad

Resumen:

$$S = B(1 - e^{-at_p}) + Ct_p$$

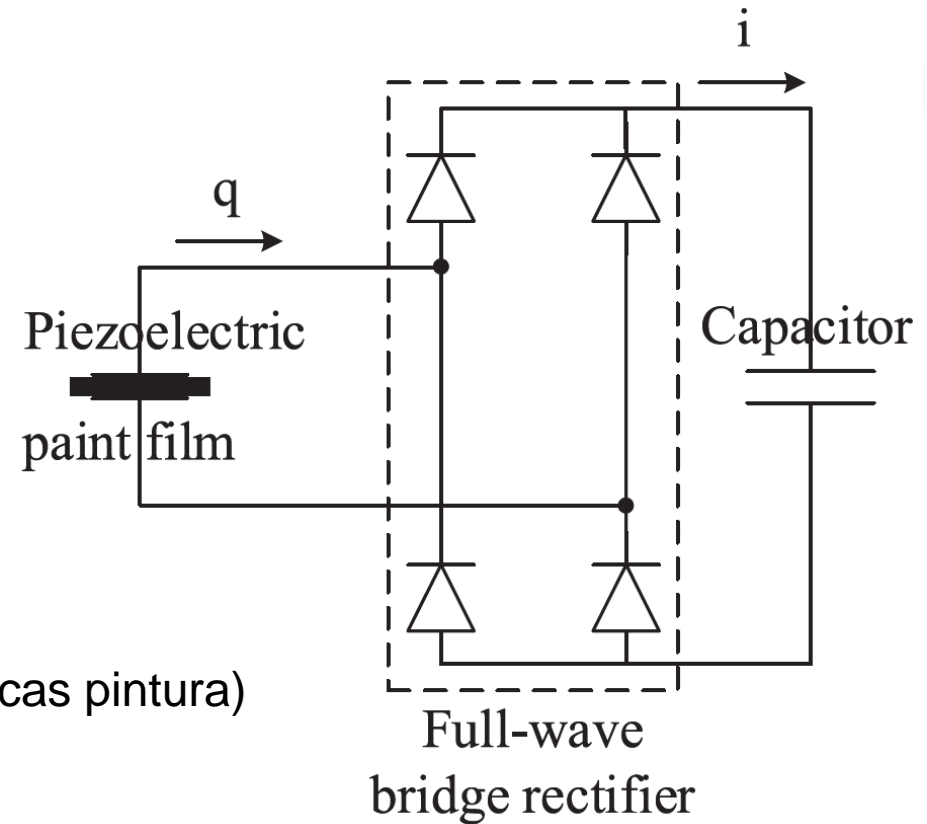
Pintura piezoeléctrica como generador



$$P = f(A, \omega, R_L, \text{características pintura})$$

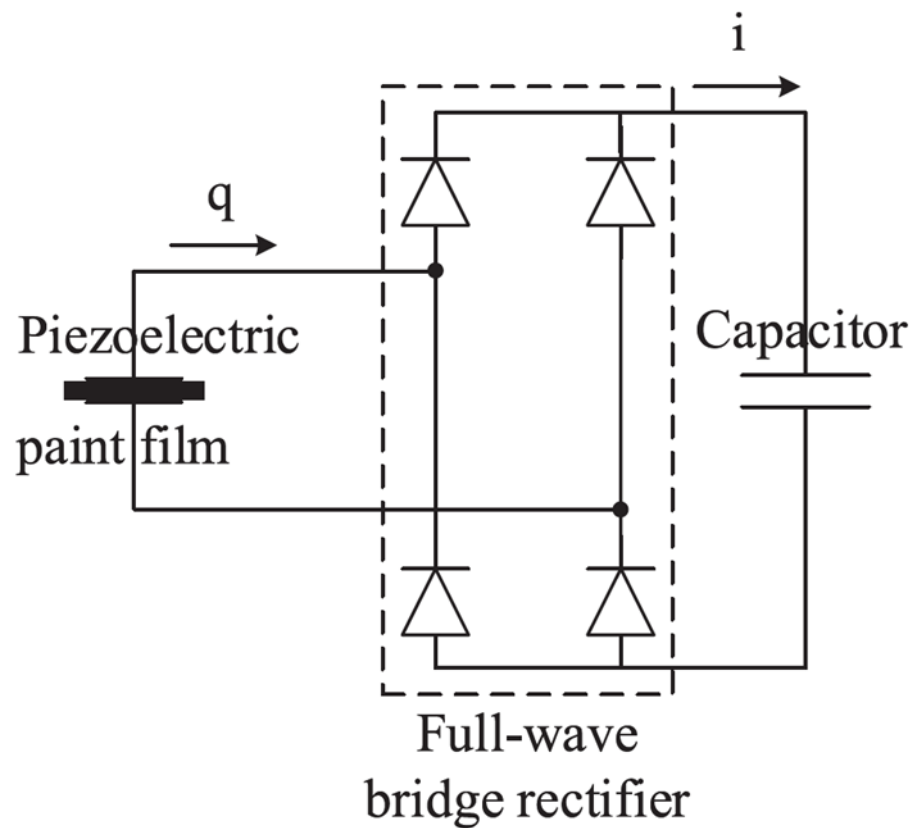
$$P_R = V_p^2 / (2R)$$

$$E = P \cdot t$$



$$E = \frac{1}{2} CV^2$$

Modelo electromecánico



$$v_c(t) = k \varepsilon_s(t)$$

$$\varepsilon_s(t_i) = \int_{t_{i-1}}^{t_i} |\dot{\varepsilon}(\tau)| d\tau + \varepsilon_s(t_{i-1})$$

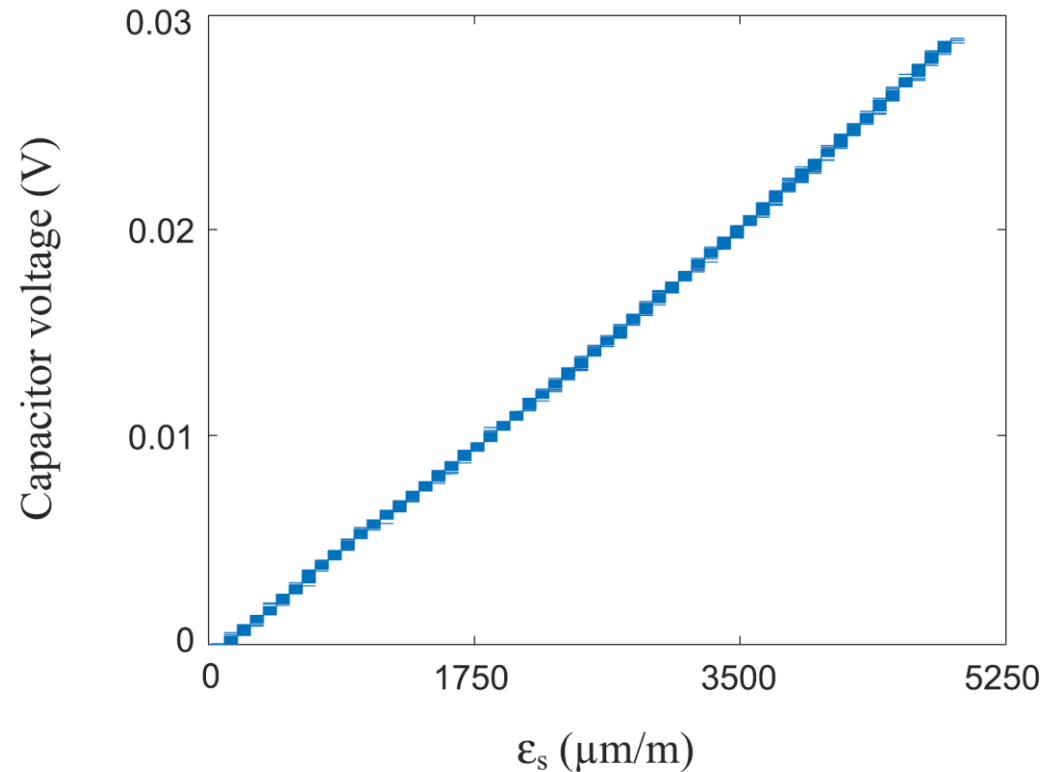
$$k = \frac{A d_{31} E}{C(1 - \nu)}$$

$$E(t) = \frac{1}{2} C k^2 \varepsilon_s^2(t)$$

Validación experimental

Tensión eléctrica en el condensador

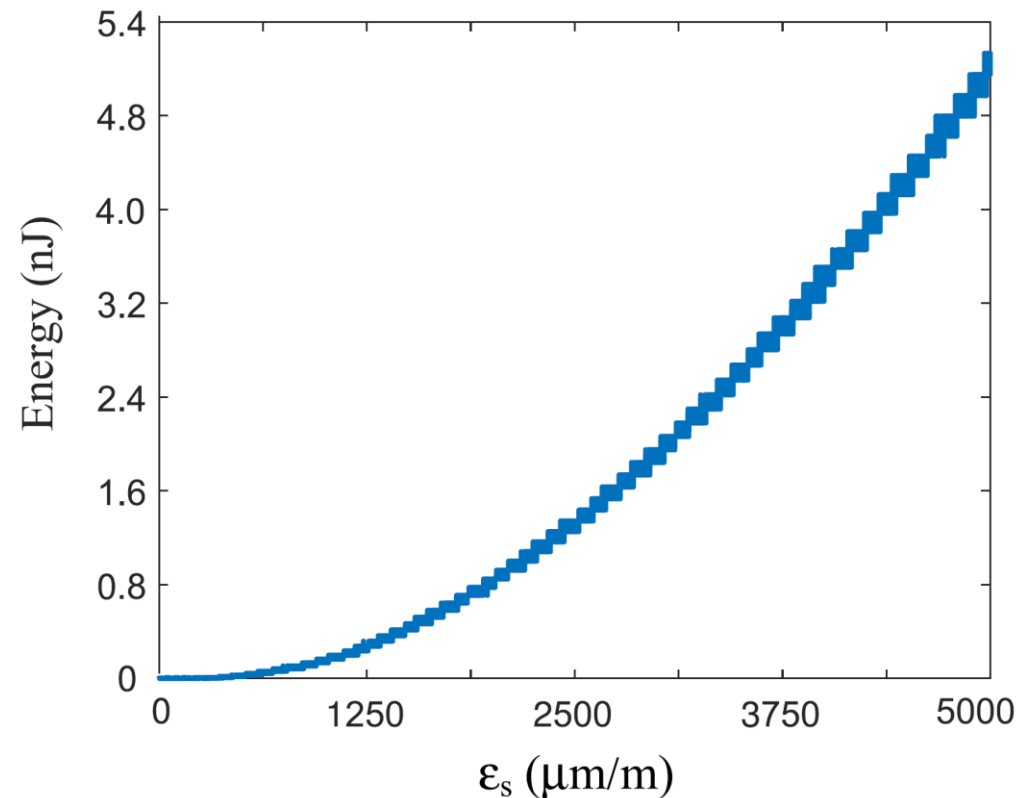
$$v_c(t) = k \varepsilon_s(t)$$



Validación experimental

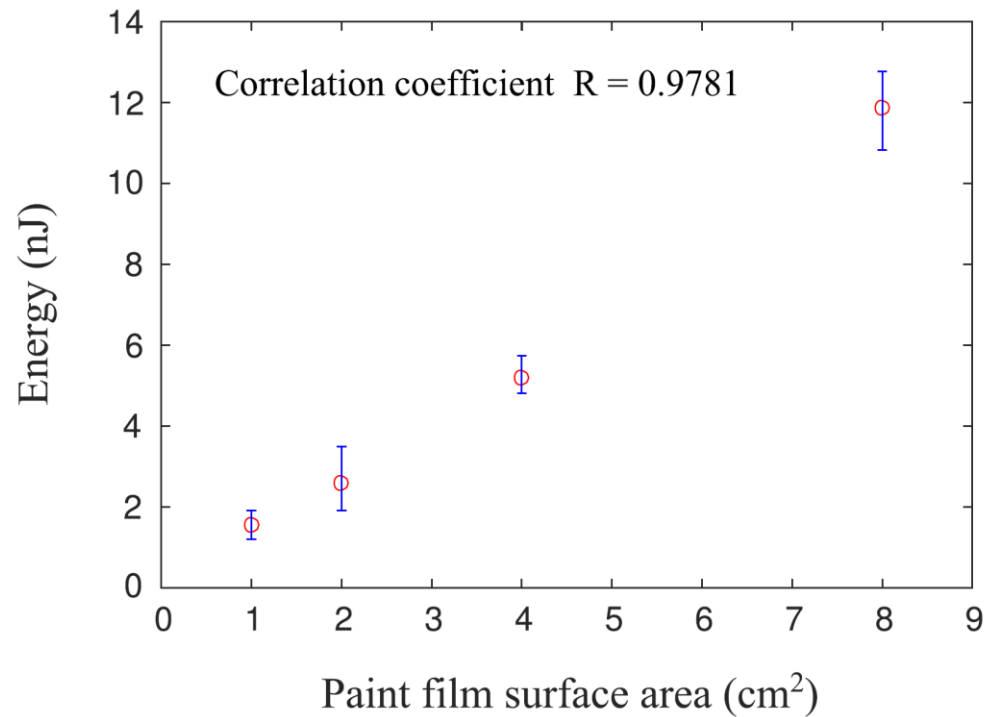
Energía eléctrica almacenada en el condensador

$$E(t) = \frac{1}{2} C k^2 \varepsilon_s^2(t)$$



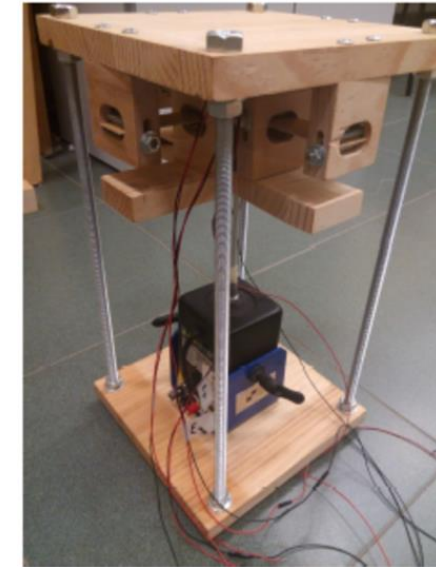
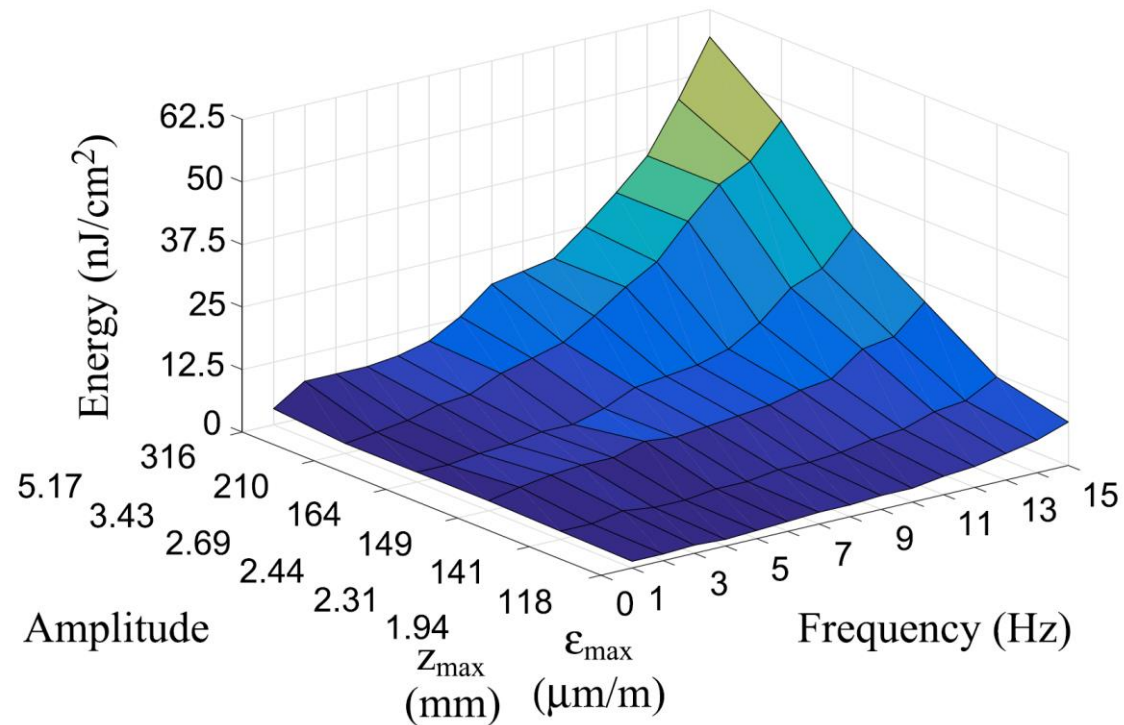
Validación experimental

Energía vs. área de la pintura piezoeléctrica



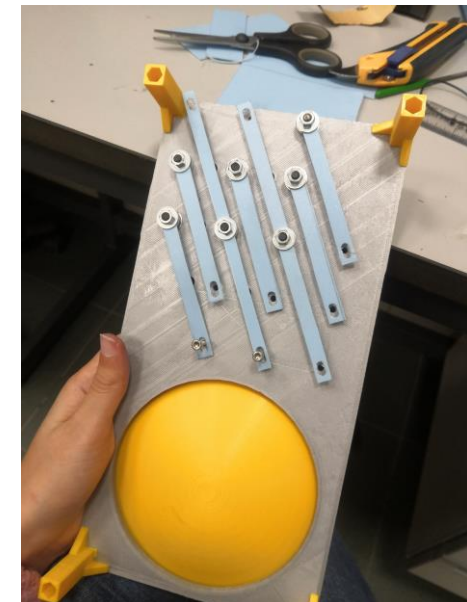
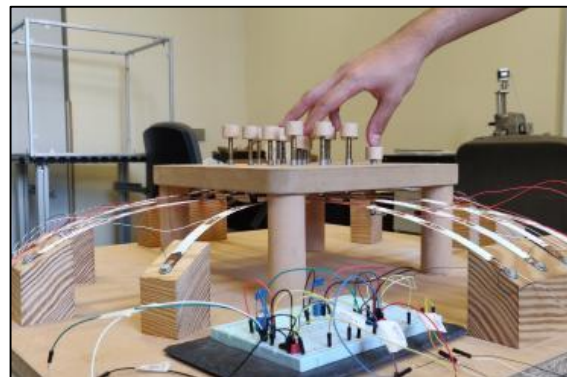
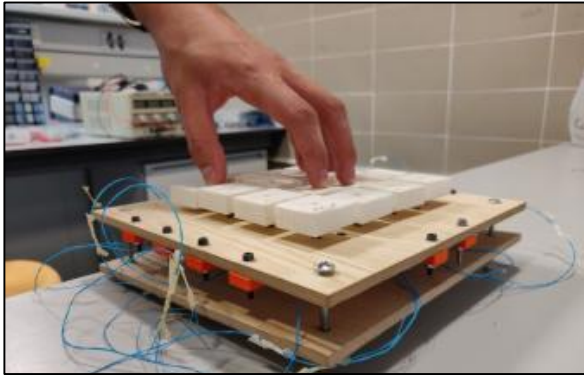
Validación experimental

Energía vs. vibración



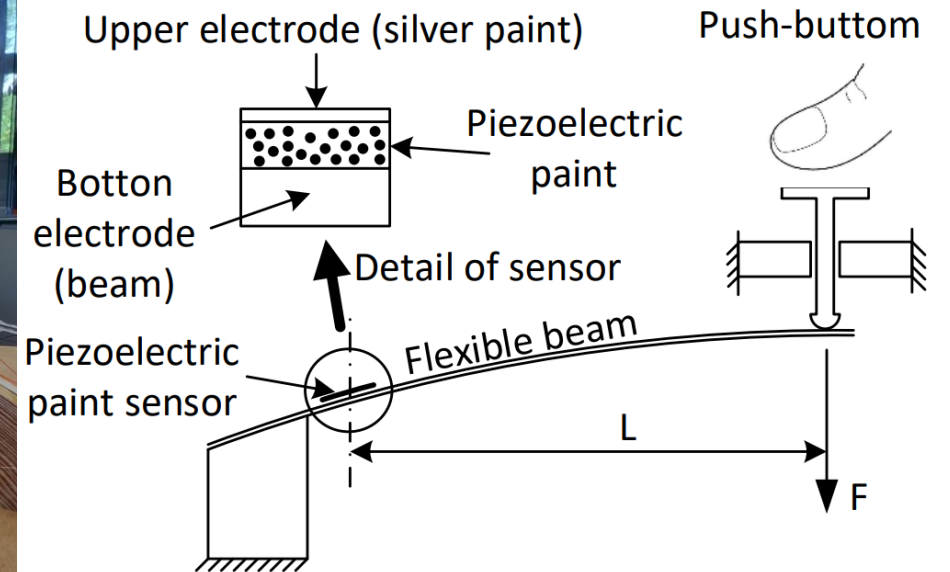
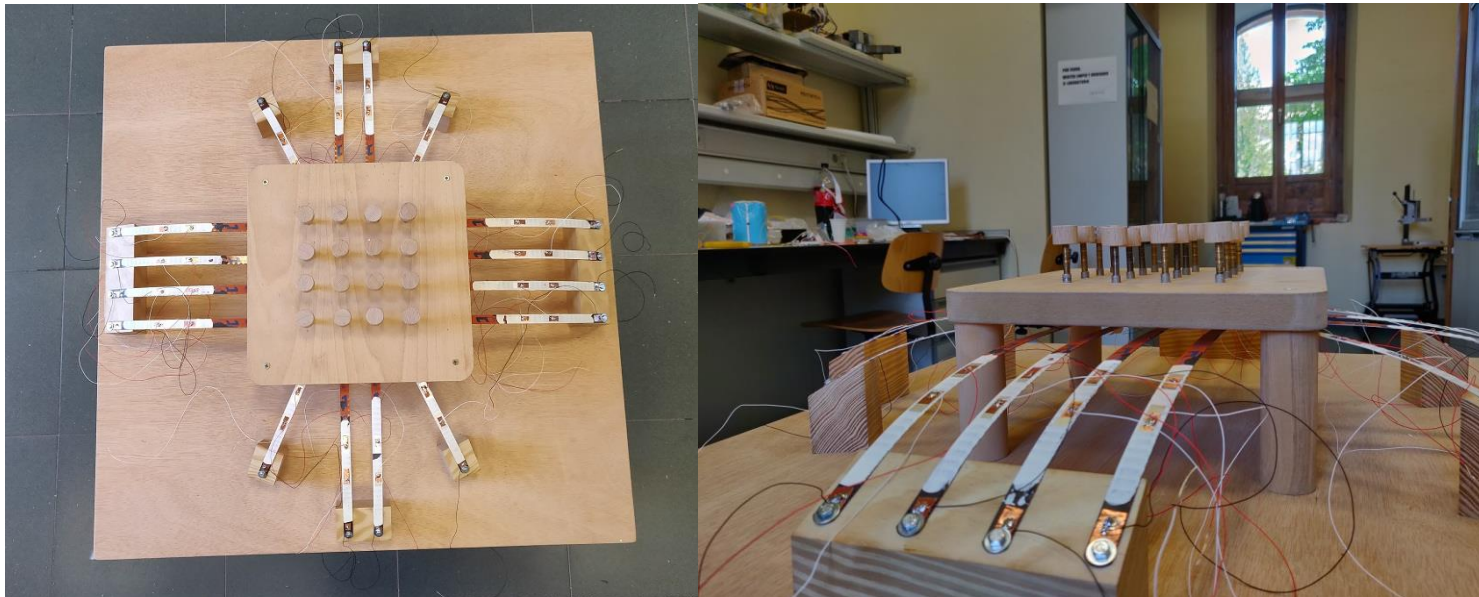
Aplicaciones desarrolladas en la UCLM

Dispositivos para la rehabilitación de la mano



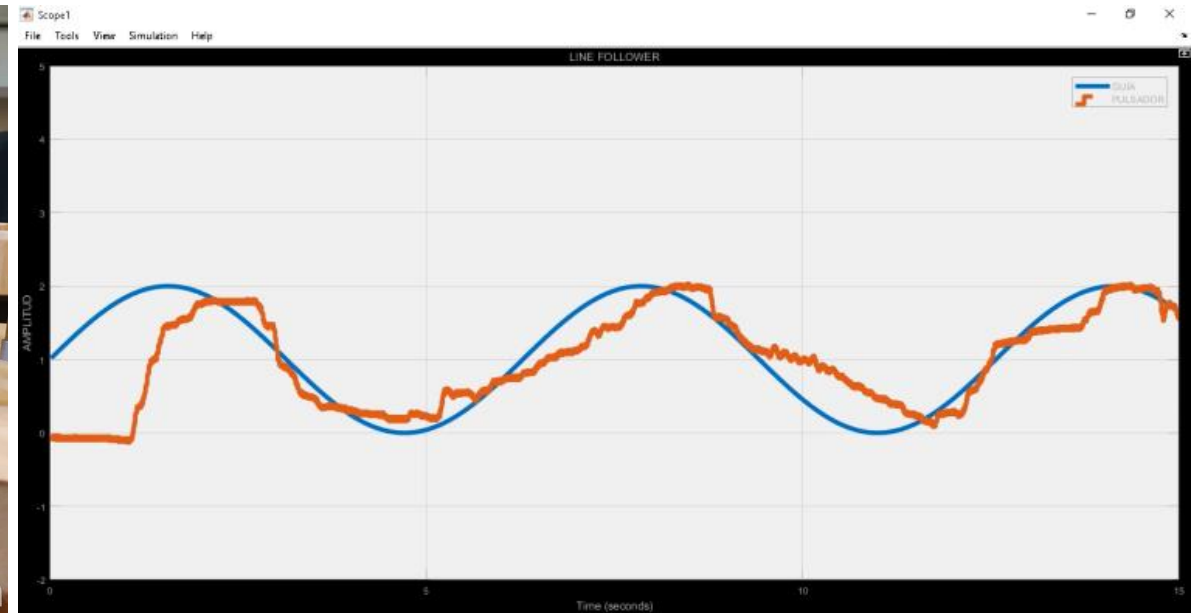
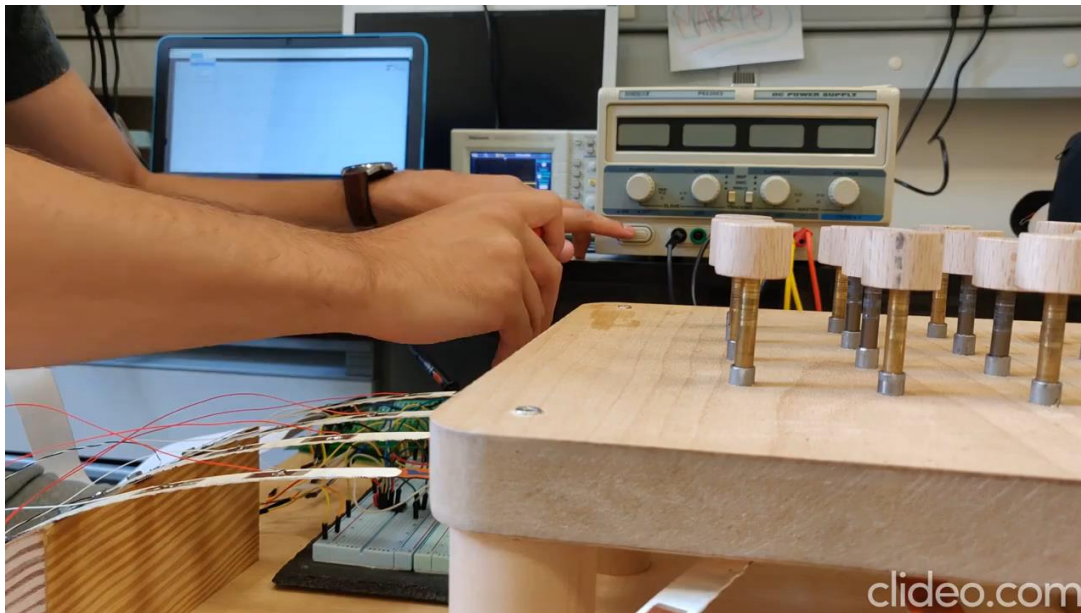
Aplicaciones desarrolladas en la UCLM

Dispositivo para la rehabilitación de la mano



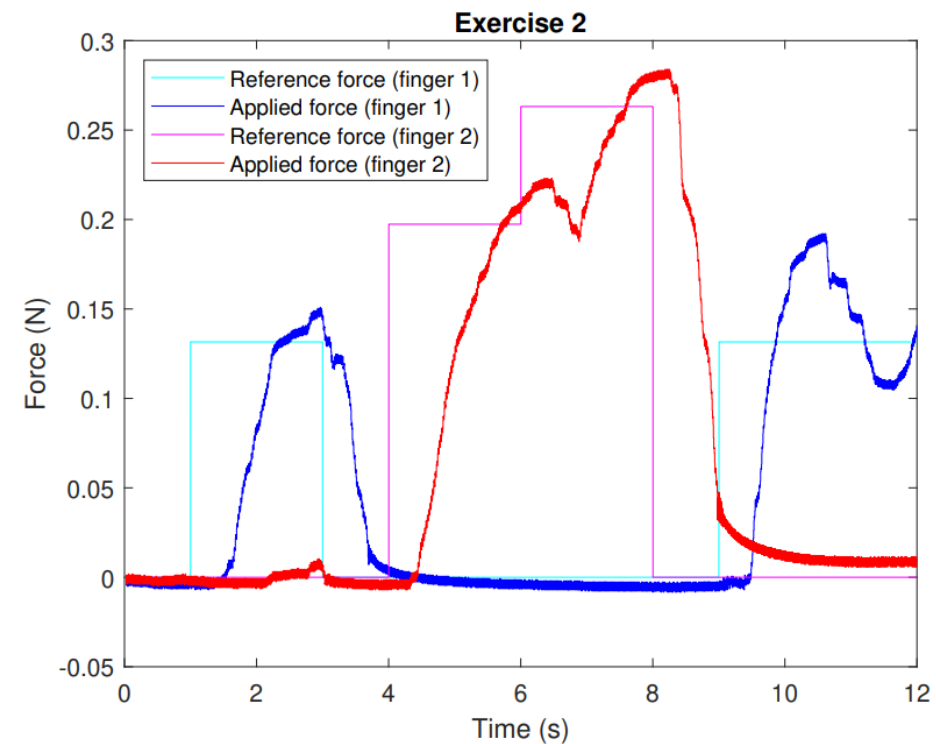
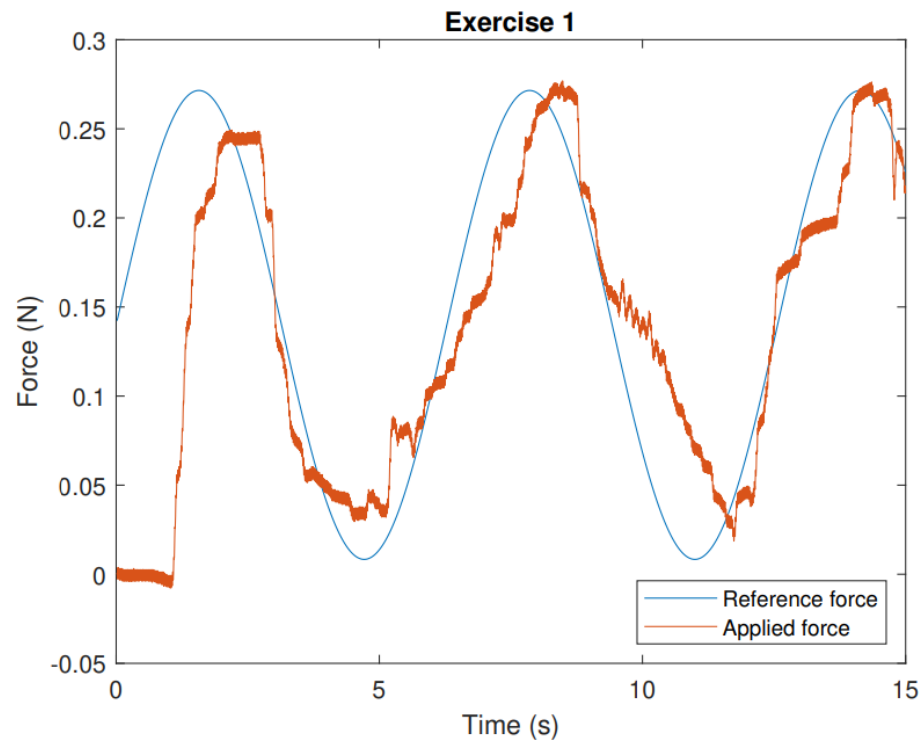
Aplicaciones desarrolladas en la UCLM

Dispositivo para la rehabilitación de la mano



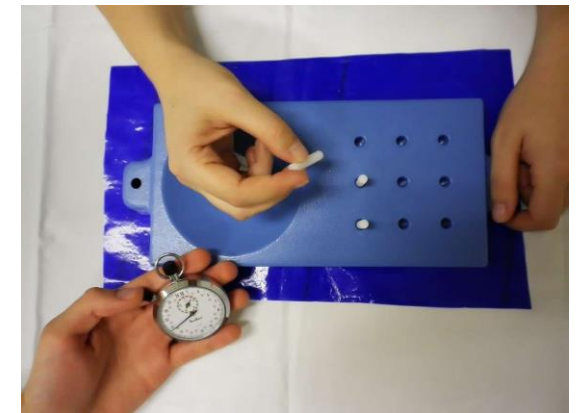
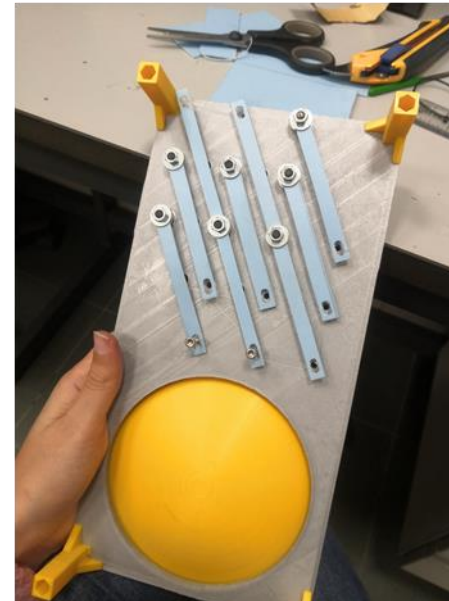
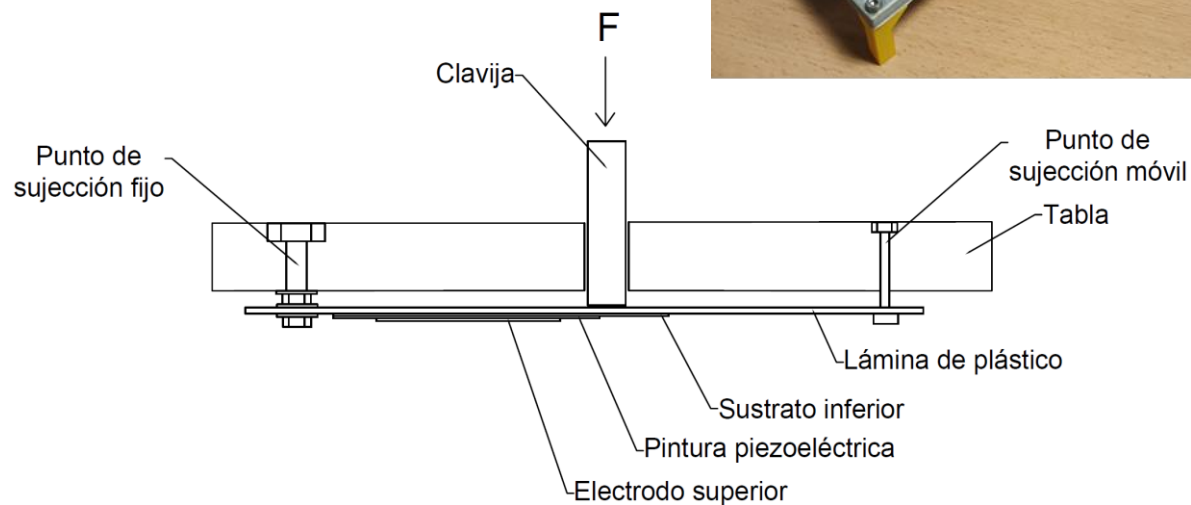
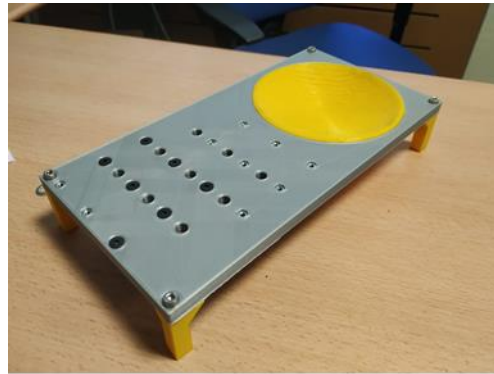
Aplicaciones desarrolladas en la UCLM

Dispositivo para la rehabilitación de la mano



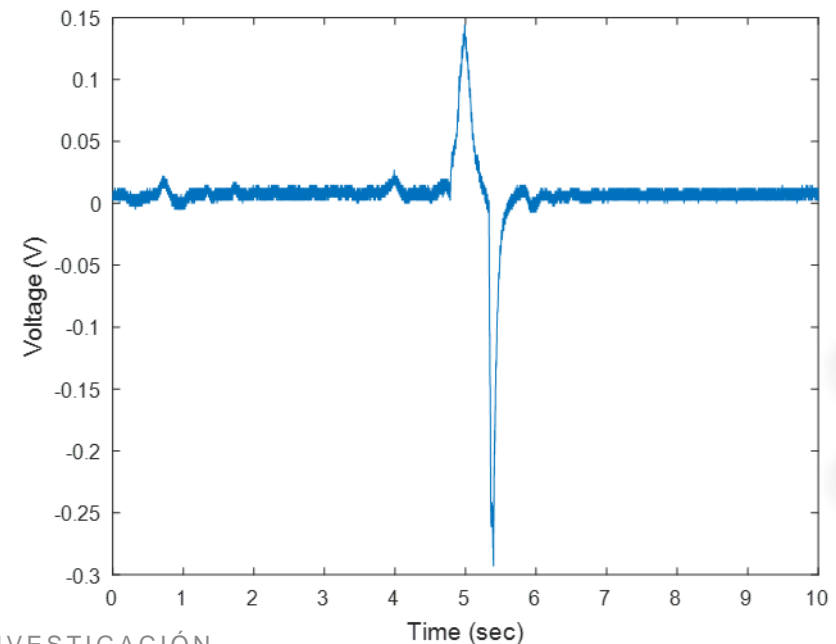
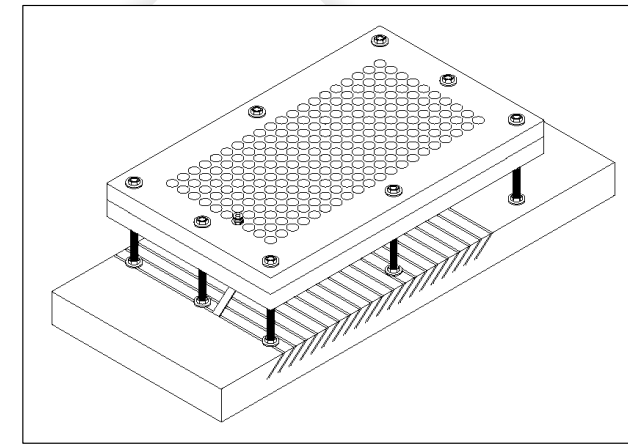
Aplicaciones desarrolladas en la UCLM

Dispositivo para la rehabilitación de la mano



Aplicaciones desarrolladas en la UCLM

Plataforma de fuerza para el análisis del paso





Muchas gracias

